

- Take the form: $ay''+by'+cy = 0$
- How to solve:
 - Guess: $y = e^{rt}$ Substitute
 - $ar^2e^{rt} + bre^{rt} + ce^{rt} = 0$ e^{rt} is never 0, so cancel
 - $ar^2 + br + c = 0$ This is the **characteristic equation** for r .
 - $r = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$ Use quadratic formula to solve for r .
- Cases:
 - **Overdamped:** two distinct, real roots (i.e. $b^2 - 4ac > 0$)
 - Let r_1 and r_2 solve the characteristic equation. $r_1 \neq r_2$
 - $\therefore y_1 = e^{r_1 t}$ and $y_2 = e^{r_2 t}$ are solutions to $ay''+by'+cy = 0$
 - General solution: $y = c_1 e^{r_1 t} + c_2 e^{r_2 t}$ (apply superposition)
 - **Critically damped:** one repeated real root (i.e. $b^2 - 4ac = 0$)
 - General solution: $y = c_1 e^{rt} + c_2 t e^{rt}$
 - This is most easily proved with the Laplace transform
 - **Underdamped:** two complex roots (i.e. $b^2 - 4ac < 0$)
 - Let the roots be $r = a \pm bi$
 - General solution: $y = e^{at}(c_1 \cos bt + c_2 \sin bt)$
 - Theorem: If a complex solution y solves a linear homogeneous differential equation, then $\text{Re}[y]$ and $\text{Im}[y]$ are also solutions. Proof with substitution and superposition.
 - Proof of general solution:
 - $y = e^{(a \pm bi)t} = e^{at} e^{i(\pm bt)}$
 - $y = e^{at} \text{cis}(\pm bt)$. Use Euler's formula.
 - $y_1 = e^{at} \cos(bt)$ and $y_2 = \pm e^{at} \sin(bt)$. Apply theorem.
 - $y = e^{at}(c_1 \cos bt + c_2 \sin bt)$. Apply superposition.
 - **Free:** $b = 0$
 - Let the roots be $r = \pm bi$
 - General solution $y = c_1 \cos bt + c_2 \sin bt$
- Applications
 - Unforced mass-spring system with damping $mx''+cx'+kx = 0$
 - RLC circuit: $Lq''+Rq'+\frac{q}{C} = 0$; LC circuit: $Lq''+\frac{q}{C} = 0$
 - Simple harmonic motion.
 - Pendulums (approximated model using the small angle approximation $\theta'' + \frac{g}{L}\theta = 0$). $\theta'' + \frac{g}{L}\sin\theta = 0$ is the more accurate model.
 - Unforced mass-spring system without damping $mx''+kx = 0$